



towards Digital Single Market

MATERIALS MODELLING



Data and documentation

terminology, classification and ontology

COMMON terminology and classification

EFFICIENT COMMUNICATION

Dr. Anne F de Baas, EC



Review of Materials Modelling (RoMM version V and VI)

http://ec.europa.eu/research/industrial_technologies/modelling-materials_en.html



RESEARCH & INNOVATION

Key Enabling Technologies

European Commission > Research & Innovation > Key Enabling Technologies > eLibrary



-  **Nanotechnologies**
-  **Advanced Materials**
-  **Advanced Manufacturing**
-  **Public Private Partnerships**
-  **Biotechnologies**
-  **Coal and Steel (RFCS)**
-  **Innovation and Impact**

Publications, Reports

For more publications please visit the [EU Bookshop](#)

Review of Materials Modelling

(This version IV replaces the "Brochure for Materials Modelling")



Communication between the fields will be facilitated by a commonly understood vocabulary. This vocabulary has been adapted based on extensive discussions.

The notion "meta data" has been introduced and we hope it will be used to describe models, simulation and experiment results and facilitate interoperability of different models.

We believe we have proven the vocabulary is useful by applying it to now about 100 project fiches.

Our impressions are that people have accepted the classification of models according to their physics/chemistry as the classification via application size is not unique. With this follows the separation between the notions "mesoscopic" and "mesoscale".

Share 

Key Enabling Technologies

- ▶ [How to get funding ?](#)
- ▶ [Horizon 2020](#)
- ▶ [e-Library](#)
- ▶ [Help and Advice](#)

Success Stories

A selection of articles about [EU funded Research & Innovation projects](#) from across Europe.

For more publications please visit





Review of Materials Modelling (RoMM version V and VI)

Standardised vocabulary and classification

Taxonomy CEN/CENELEC CWA

<https://www.cen.eu/news/workshops/Pages/WS-2017-012.aspx> .



This common language can form the basis for an **ontology** with a formal language of materials modelling and a definition of the relation between the concepts.

Such an ontology can then be a basis for metadata development necessary for a Modelling Market Place.

First draft EMMO (see presentation yesterday)



MODA a unified presentation

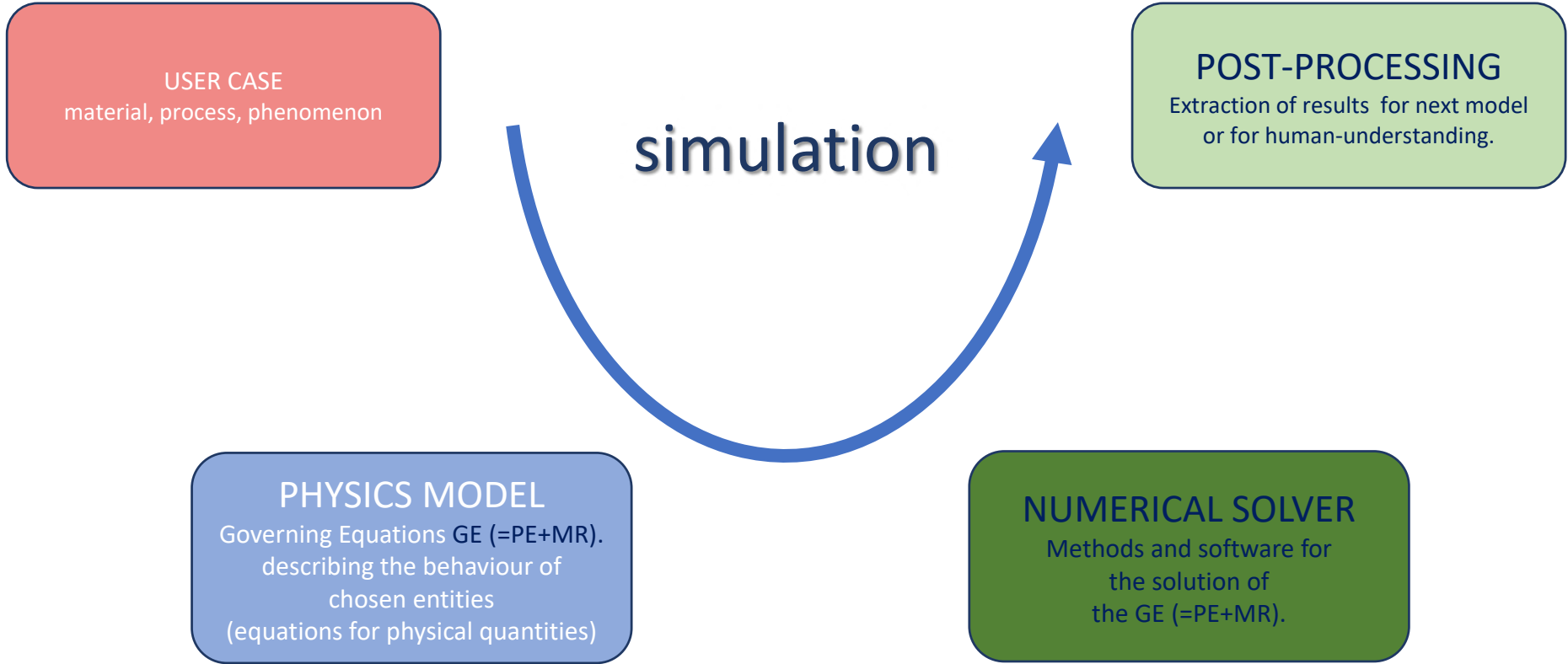
MODA organise the documentation of a simulation into four tables

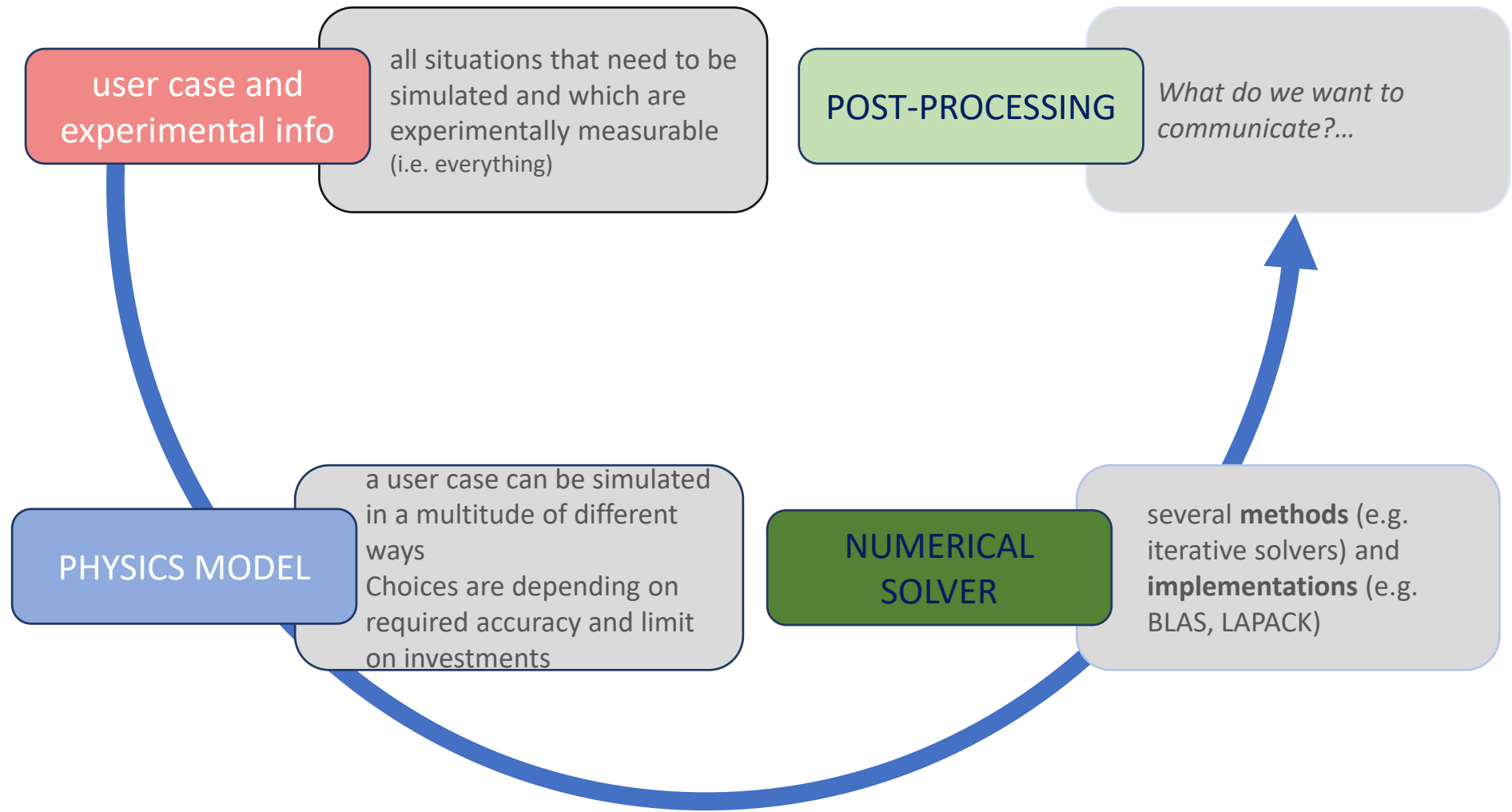
The tables take the modeller by the hand.
They ask the relevant questions step by step.

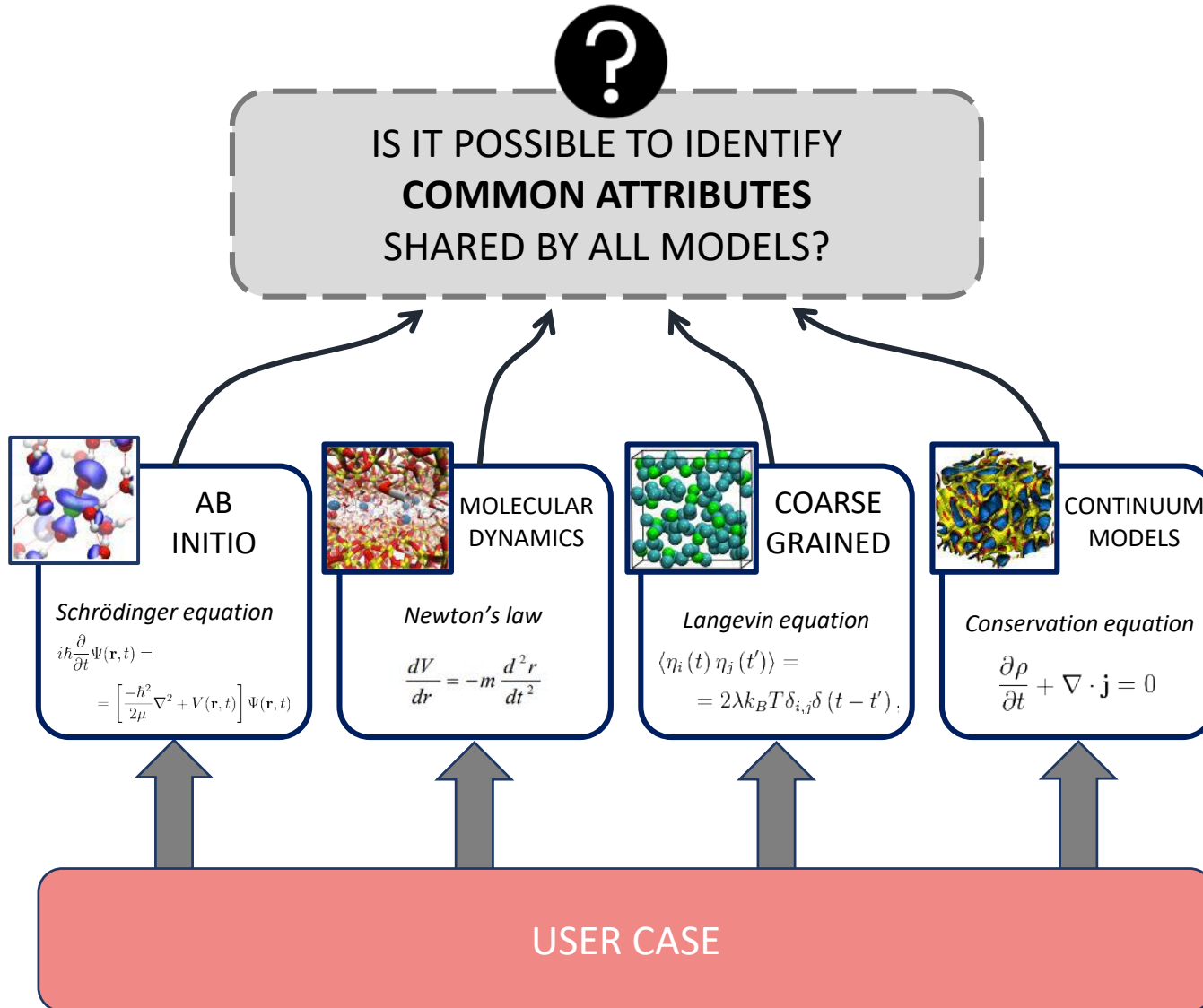
MODA are understandable by non –modellers.

We have proven  ALL simulations can be described with this standard.

The templates and examples for the MODA standardised description can be found on (<https://emmc.info/moda/>)







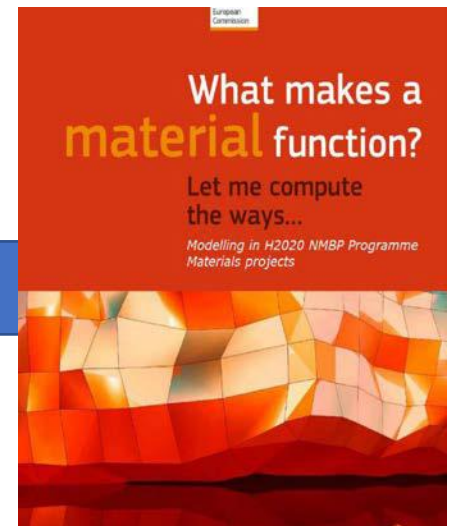
a first step in the direction of a standardised description of modelling has been taken by the EC

MODA (MOdelling DAta)

is a **template** for the **standardised description** of **materials models**
(<https://emmc.info/moda-workflow-templates/>)

The **MODA** is meant to **guide users** towards a complete **high-level documentation** of material models, starting from the **end-user case** via the **computational details** to the **results**.

It provides all necessary aspects for: **description**, **reproducibility**, **curation** and **interfacing** with other models and databases.



*Modelling in
H2020 LEIT-NMBP Programme
Materials and Nanotechnology projects*

Review of Materials Modelling VI
RoMM

Vocabulary, classification and metadata for materials modelling
(130 FP7 and H2020 projects)

<https://bookshop.europa.eu/en/what-makes-a-material-function--pbKI0616197/>

The MODA uses **core model concepts**

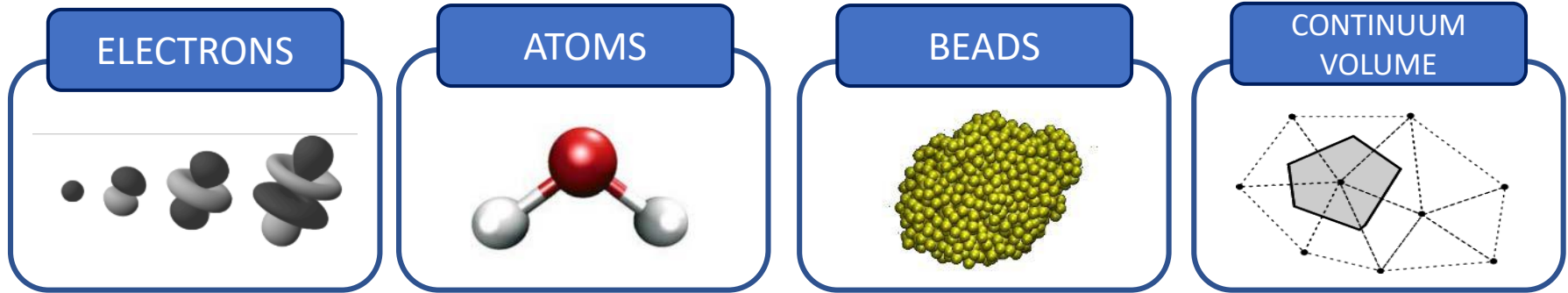
PHYSICS ENTITY

EQUATIONS
(physics- or data-based)

IN THE **MODA**, physics-based MATERIALS MODELS ARE CLASSIFIED VIA



WHOSE BEHAVIOUR IS DESCRIBED BY PHYSICS



Bead: Discrete entity consisting of more than one atom (e.g. groups of atoms, nanoparticles, grains).

Continuum Volume: Volume in which the material properties are averaged.

The classification is

- not** according to the **size** of the application or system
- nor** according to the **length scale** of the phenomena to be simulated
- nor** according to the **solver type**

PHYSICS-BASED MODEL

PHYSICS EQUATION

PE

Equation based on a **physics/chemistry theory** which describes the spatial and temporal evolution of physics quantities of the entity

PHYSICS QUANTITIES

MATERIAL RELATIONS

MR

Information on the material needed to **close the PE** and to make the system of Governing Equations **solvable**

EXAMPLES

CLASSICAL MOLECULAR DYNAMICS

PE

Newton's equation of motion

$$\frac{dV}{dr} = -m \frac{d^2 r}{dt^2}$$

MR

Lennard-Jones potential

$$V_{LJ} = 4\epsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right]$$

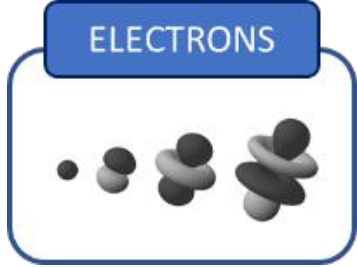
FLUID DYNAMICS

Navier Stokes equation

$$\text{PE} \quad \frac{\partial}{\partial t}(\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) = -\nabla \cdot p \mathbf{I} + \nabla \cdot \boldsymbol{\tau} + \rho \mathbf{g}$$

Stress tensor for incompressible flows

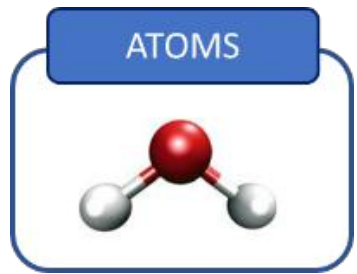
$$\text{MR} \quad \nabla \cdot \boldsymbol{\tau} = 2\mu \nabla \cdot \boldsymbol{\varepsilon} = \mu \nabla \cdot (\nabla \mathbf{u} + \nabla \mathbf{u}^T) = \mu \nabla^2 \mathbf{u}$$



ELECTRONIC MODEL

Physics Based Model using a Physics Equation and Material Relation describing the behaviour of electrons and quasi particles either as waves, particles or distributions.

- 1.1 *Schrödinger Equation based models*
 - Single particle Schrödinger models*
 - Many body Schrödinger models*
 - Quantum mechanical time dependant Schrödinger models*
- 1.2 *Kohn Sham equation Density Functional Theory (electronic DFT)*
- 1.3 *Quantum Dynamic Mean Field Theory*
- 1.4 *NEGF*
- 1.5 *Statistical charge transport model*
- 1.6 *Statistical spin transport model*



ATOMISTIC MODELS

Physics Based Model using a Physics Equation and Material Relation describing the behaviour of atoms either as waves, particles or distributions.

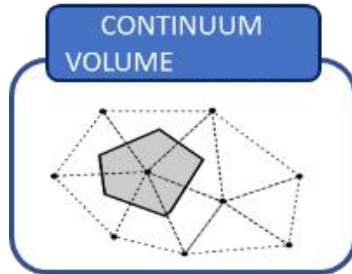
- 2.1 *Classical Density Functional Theory and Dynamic DFT*
- 2.2 *Newton's equation based models*
- 2.3. *Statistical Mechanics atomistic models*
- 2.4 *Atomistic spin models*
- 2.5 *Statistical transport model at atomistic level*
- 2.6 *Atomistic phonon-based models (Boltzmann Transport Equation)*



MESOSCOPIC MODELS

Physics Based Model using a Physics Equation and Material Relation describing the behaviour of Beads either as waves, particles or distributions.

- 3.1 Mesoscopic Classical Density Functional Theory and Dynamic DFT
- 3.2 Coarse-Grained Molecular Dynamics and Dissipative Particle Dynamics
- 3.3 Statistical Mechanics mesoscopic models
- 3.4 Micromagnetic models
- 3.5 Mesoscopic phonon models (Boltzmann Transport Equation)



CONTINUUM MODELS

Physics Based Model using a Physics Equation and Material Relation describing the behaviour of Continuum Volume.

- 4.1 Solid Mechanics
- 4.2 Fluid Mechanics
- 4.3 Heat Flow and Thermo-mechanical behaviour
- 4.4 Continuum Thermodynamics and Phase Field models
- 4.5 Chemistry reaction (kinetic) models (continuum)
- 4.6 Electromagnetism (incl optics, magnetics and electrical)
Processes and Devices



HOW IT LOOKS!

MODA for <user-case> Simulated in project <acronym>

OVERVIEW of the SIMULATION	
1	<p>USER CASE</p> <p>General description of the User Case.</p> <p>Please give the properties and behaviour of the particular material, manufacturing process and/or in-service-behaviour to be simulated. No information on the modelling should appear here. The idea is that this user-case can also be simulated by others with other models and that the results can then be compared.</p>
2	<p>CHAIN OF MODELS</p> <p>MODEL 1</p> <p>Please identify the first model. Note these are assumed to be physics-based models unless it is specified differently. Most modelling projects consist of a chain of models, (workflow). Here only the Physics Equations should be given and only names appearing in the content list of the Review of Materials Modelling VI should be entered. This review is available on http://ec.europa.eu/research/industrial_technologies/e-library.cfm. All models should be identified as electronic, atomistic, mesoscopic or continuum.</p> <p>MODEL 2</p> <p>DATA-BASED MODEL</p> <p>Please identify the second model. If data-based models are used, please specify.</p>
3	<p>PUBLICATION PEER-REVIEWING THE DATA</p> <p>Please give the publication which documents the data of this ONE simulation. This article should ensure the quality of this data set (and not only the quality of the models).</p>
4	<p>ACCESS CONDITIONS</p> <p>Please list whether the model and/or data are free, commercial or open source. Please list the owner and the name of the software or database (include a web link if available).</p>
5	<p>WORKFLOW AND ITS RATIONALE</p> <p>Please give a textual rationale of why you as a modeller have chosen these models and this workflow, knowing other modellers would simulate the same end-user case differently. This should include the reason why a particular aspect of the user case is to be simulated with a particular model.</p>

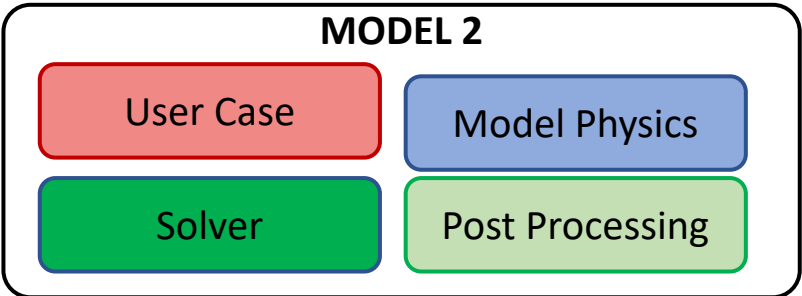
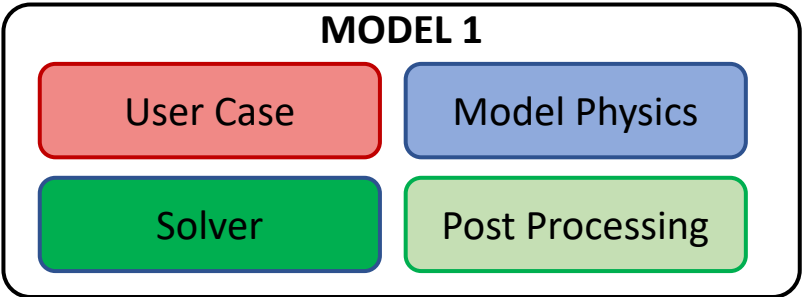
1 ASPECT OF THE USER CASE/SYSTEM TO BE SIMULATED	
1.1	<p>ASPECT OF THE USER CASE TO BE SIMULATED</p> <p>Describe the aspects of the User Case textually.</p> <p>No modelling information should appear in this box. This case could also be simulated by other models in a benchmarking operation! The information in this chapter can be end-user information, measured data, library data etc. It will appear in the pink circle of your workflow picture.</p> <p>Simulated input which is calculated by another model should not be included (but this input is listed in chapter 2.4)</p> <p>Also the result of pre-processing necessary to translate the user case specifications to values for the physics variables of the entities can be documented here.</p>
1.2	<p>MATERIAL</p> <p>Chemical composition, ...</p>
1.3	<p>GEOMETRY</p> <p>Size, form, picture of the system (if applicable)</p> <p>Note that computational choices like simulation boxes are to be documented in chapter 3.</p>
1.4	<p>TIME LAPSE</p> <p>Duration of the User Case to be simulated.</p> <p>This is the duration of the situation to be simulated. This is not the same as the computational times to be given in chapter 3.</p>
1.5	<p>MANUFACTURING PROCESS OR IN-SERVICE CONDITIONS</p> <p>If relevant, please list the conditions to be simulated (if applicable).</p> <p>E.g. heated walls, external pressures and bending forces. Please note that these might appear as terms in the PE or as boundary and initial conditions, and this will be documented in the relevant chapters.</p>
1.6	<p>PUBLICATION ON THIS DATA</p> <p>Publication documenting the simulation with this single model and its data (if available and if not already included in the overall publication).</p>

3 SOLVER AND COMPUTATIONAL TRANSLATION OF THE SPECIFICATIONS	
3.1	<p>NUMERICAL SOLVER</p> <p>Please give name and type of the solver. E.g. Monte Carlo, SPH, FE, ...iterative, multi-grid, adaptive,...</p>
3.2	<p>SOFTWARE TOOL</p> <p>Please give the name of the code and if this is your own code, please specify if it can be shared with an eventual link to a website/publication.</p>
3.3	<p>TIME STEP</p> <p>If applicable, please give the time step used in the solving operations. This is the numerical time step and this is not the same as the time lapse of the case to be simulated (see 1.4)</p>
3.4	<p>COMPUTATIONAL REPRESENTATION</p> <p>PHYSICS EQUATION, MATERIAL RELATIONS, MATERIAL</p> <p>Computational representation of the Physics Equation, Materials Relation and material.</p> <p>There is no need to repeat User Case info. "Computational" means that this only needs to be filled in when your computational solver represents the material, properties, equation variables, in a specific way.</p>
3.5	<p>COMPUTATIONAL BOUNDARY CONDITIONS</p> <p>If applicable.</p> <p>Please note that these can be translations of the physical boundary conditions set in the User Case or they can be pure computational like e.g. a unit cell with mirror b.c. to simulate an infinite domain.</p>
3.6	<p>ADDITIONAL SOLVER PARAMETERS</p> <p>Please specify pure internal numerical solver details (if applicable), like</p> <ul style="list-style-type: none"> • specific tolerances, • out-off convergence criteria • integrator options

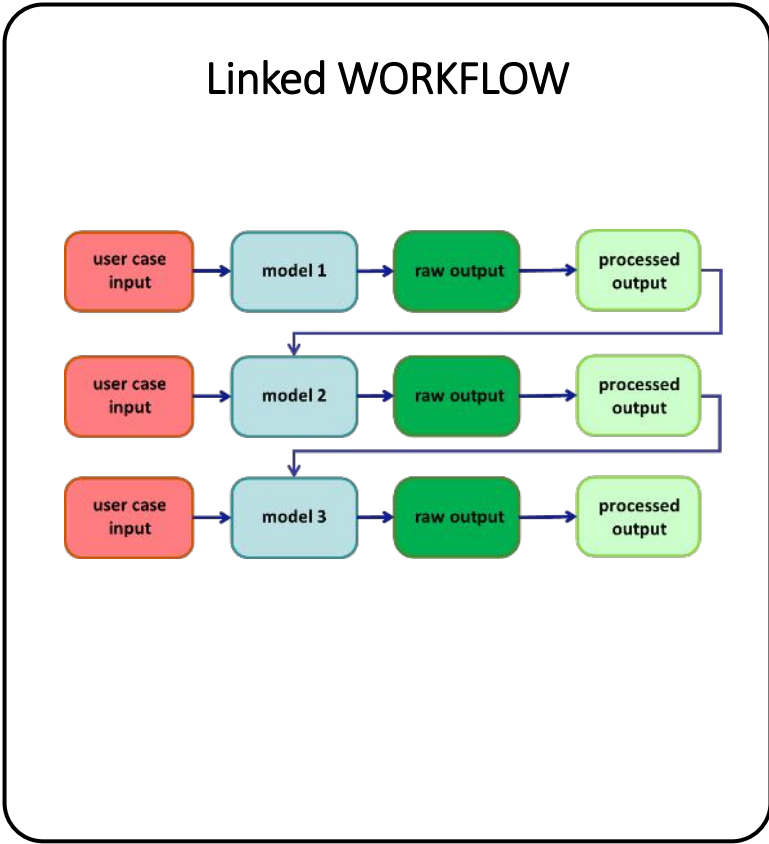
2 GENERIC PHYSICS OF THE MODEL EQUATION	
2.0	<p>MODEL TYPE AND NAME</p> <p>Model type and name chosen from RoMM content list (the PE).</p> <p>This PE and only this will appear in the blue circle of your workflow picture. Please do not insert any other text although an indication of the MR is allowed.</p>
2.1	<p>MODEL ENTITY</p> <p>The entity in this materials model is <finite volumes, grains, atoms, or electrons></p>
2.2	<p>MODEL PHYSICS/CHEMISTRY EQUATION PE</p> <p>Equation</p> <p>Name, description and mathematical form of the PE</p> <p>In case of tightly coupled PEs set up as one matrix which is solved in one go, more than one PE can appear.</p> <p>Physical quantities</p> <p>Please name the physics quantities in the PE, these are parameters (constants, matrices) and variables that appear in the PE, like wave function, Hamiltonian, spin, velocity, external force.</p> <p>Relation</p> <p>Please, give the name of the Material Relation and which PE it completes.</p>
2.3	<p>MATERIALS RELATIONS</p> <p>Physical quantities/descriptors for each MR</p> <p>Please give the name of the physics quantities, parameters (constants, matrices) and variables that appear in the MR(s).</p>
2.4	<p>SIMULATED INPUT</p> <p>Please document the simulated input and with which model it is calculated.</p> <p>This box documents the interoperability of the models in case of sequential or iterative model workflows. Simulated output of the one model is input for the next model. Thus what you enter here in 2.4 will also appear in 4.1 of the model that calculated this input.</p> <p>If you do simulations in isolation, then this box will remain empty.</p> <p>Note that all measured input is documented in chapter 1 "User Case".</p>

4 POST PROCESSING	
4.1	<p>THE PROCESSED OUTPUT</p> <p>Please specify the output obtained by the post processing.</p> <p>If applicable then specify the entity in the next model in the chain for which this output is calculated: electrons, atoms, grains, larger/smaller finite volumes.</p> <p>In case of homogenisation, please specify the averaging volumes.</p> <p>Output can be calculated values for parameters, new MR and descriptor rules (data-based models).</p>
4.2	<p>METHODOLOGIES</p> <p>Please describe the mathematics and/or physics used in this post-processing calculation.</p> <p>In homogenisation this is volume averaging. But also physics equations can be used to derive e.g. thermodynamics quantities or optical quantities from Quantum Mechanics raw output.</p>
4.3	<p>MARGIN OF ERROR</p> <p>Please specify the margin of error (accuracy in percentages) of the property calculated and explain the reasons to an industrial end user.</p>

OVERVIEW OF THE SIMULATION



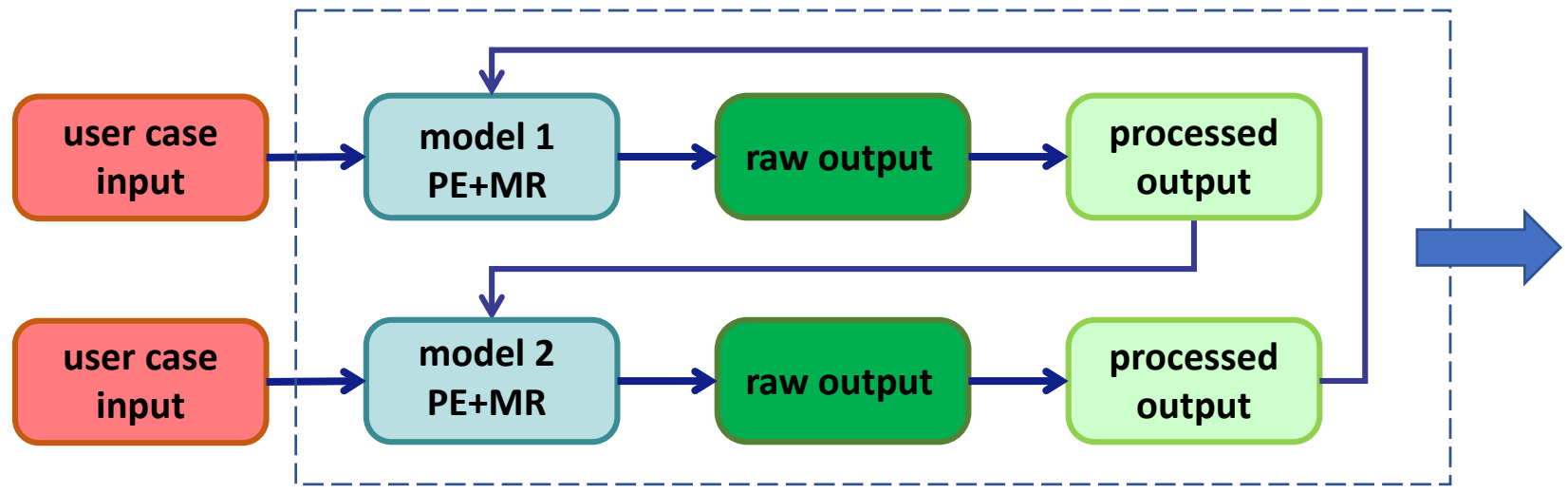
...



MODA WORKFLOW

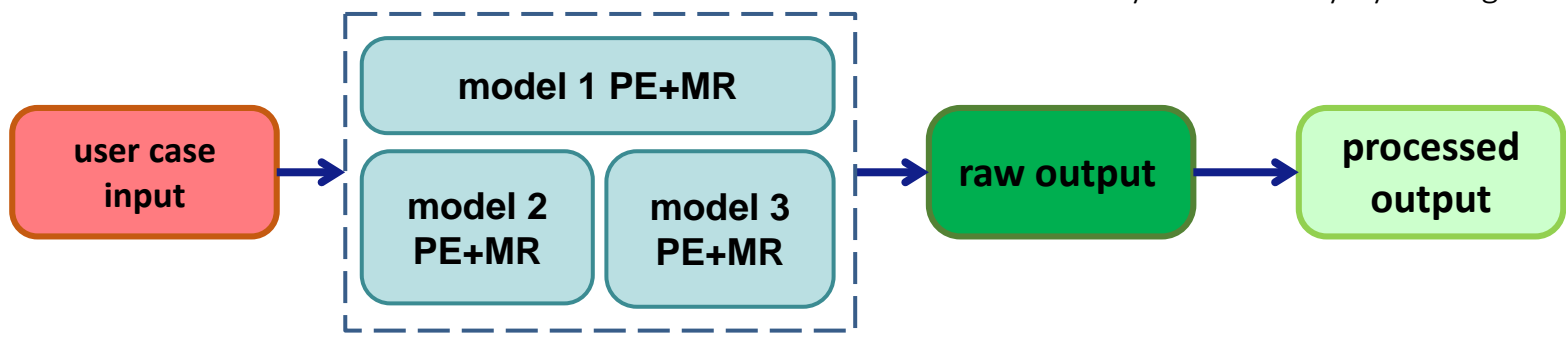
workflow for an iterative chain

Iterative solution of segregated equations



workflow for tightly coupled models

equations solved together
(running different models for the same entity concurrently by solving one matrix)



OVERVIEW of the SIMULATION		
USER CASE	<p><i>General description of the User Case: properties and behaviour of the particular material, manufacturing process and/or in-service-behaviour to be simulated.</i></p> <p><i>No information on the modelling should appear here. The idea is that this user-case can also be simulated by others with other models and that the results can then be compared.</i></p>	
CHAIN OF MODELS	MODEL 1	<i>Please identify all models used in this simulation. Note these are assumed to be physics-based models unless it is specified differently.</i>
	MODEL 2	
	...	<i>Most modelling projects consist of a chain of models (workflow).</i>
	MODEL N	<i>Only names appearing in the content list of the Review of Materials Modelling VI should be entered. All models should be identified as electronic, atomistic, mesoscopic or continuum.</i>
	DATA-BASED MODEL	<i>If data-based models are used, please specify.</i>
PUBLICATION PEER-REVIEWING THE DATA	<p><i>The publication which documents the data of this ONE simulation.</i></p> <p><i>This article should ensure the quality of this data set (and not only the quality of the models).</i></p>	
ACCESS CONDITIONS	<i>List whether the model and/or data are free, commercial or open source and the owner and the name of the software or database (include a web link if available).</i>	
WORKFLOW AND ITS RATIONALE	<p><i>Please give a textual rationale of why you as a modeller have chosen these models and this workflow, knowing other modellers would simulate the same end-user case differently. Please discuss the balance between wished for accuracy (of properties or trend predictions) and necessary investment.</i></p> <p><i>This should include the reason why a particular aspect of the user case is to be simulated with a particular model.</i></p>	

ASPECT OF THE USER CASE TO BE SIMULATED

MODEL 1, 2, ..., N (one for each model in the chain)

<p>ASPECT OF THE USER CASE TO BE SIMULATED</p>	<p><i>Describe the aspects of the User Case textually.</i></p> <p><i>No modelling information should appear in this box. This case could also be simulated by other models in a benchmarking operation!</i></p> <p><i>The information in this chapter can be end-user information, measured data, library data etc. It will appear in the pink circle of your workflow picture.</i></p> <p><i>Simulated input which is calculated by another model should not be included.</i></p> <p><i>Also the result of pre-processing necessary to translate the user case specifications to values for the physics variables of the entities can be documented here.</i></p>
<p>MATERIAL</p>	<p><i>Description of the material to be simulated (e.g. chemical composition)</i></p>
<p>GEOMETRY</p>	<p><i>Size, form, picture of the system (if applicable)</i></p>
<p>TIME LAPSE</p>	<p><i>Duration of the User Case to be simulated.</i></p> <p><i>This is the duration of the situation to be simulated. This is not the same as the computational times.</i></p>
<p>MANUFACTURING PROCESS OR IN-SERVICE CONDITIONS</p>	<p><i>If relevant, please list the conditions to be simulated (if applicable).</i></p> <p><i>e.g. heated walls, external pressures and bending forces. Please note that these might appear as terms in the PE or as boundary and initial conditions, and this will be documented in the relevant chapters</i></p>
<p>PUBLICATIONS ON THIS DATA</p>	<p><i>Publication documenting the simulation with this single model and its data (if available and if not already included in the overall publication).</i></p>

MODEL EQUATIONS						
MODEL 1, 2, ..., N (one for each model in the chain)	<p>MODEL TYPE AND NAME</p> <p><i>Model type and name chosen from RoMM content list.</i></p> <p><i>This PE and only this will appear in the blue circle of your workflow picture.</i></p>					
	<p>MODEL ENTITY</p> <p><i>The entity in this materials model is <finite volumes, beads, atoms, or electrons></i></p>					
	<table border="1"> <tr> <td rowspan="2" style="text-align: center;">MODEL PHYSICS EQUATIONS</td> <td style="text-align: center;">EQUATION</td> <td> <p>Name, description and mathematical form of the PE</p> <p><i>In case of tightly coupled PEs set up as one matrix which is solved in one go, more than one PE can appear.</i></p> </td> </tr> <tr> <td style="text-align: center;">PHYSICAL QUANTITIES</td> <td> <p><i>Please name the physics quantities in the PE, these are parameters (constants, matrices) and variables that appear in the PE, like wave function, Hamiltonian, spin, velocity, external force.</i></p> </td> </tr> </table>	MODEL PHYSICS EQUATIONS	EQUATION	<p>Name, description and mathematical form of the PE</p> <p><i>In case of tightly coupled PEs set up as one matrix which is solved in one go, more than one PE can appear.</i></p>	PHYSICAL QUANTITIES	<p><i>Please name the physics quantities in the PE, these are parameters (constants, matrices) and variables that appear in the PE, like wave function, Hamiltonian, spin, velocity, external force.</i></p>
	MODEL PHYSICS EQUATIONS		EQUATION	<p>Name, description and mathematical form of the PE</p> <p><i>In case of tightly coupled PEs set up as one matrix which is solved in one go, more than one PE can appear.</i></p>		
		PHYSICAL QUANTITIES	<p><i>Please name the physics quantities in the PE, these are parameters (constants, matrices) and variables that appear in the PE, like wave function, Hamiltonian, spin, velocity, external force.</i></p>			
	<table border="1"> <tr> <td rowspan="2" style="text-align: center;">MATERIAL RELATIONS</td> <td style="text-align: center;">RELATION</td> <td> <p><i>Please, give the name of the Material Relation and which PE it completes.</i></p> </td> </tr> <tr> <td style="text-align: center;">PHYSICAL QUANTITIES</td> <td> <p><i>Please give the name of the physics quantities, parameters (constants, matrices) and variables that appear in the MR(s)</i></p> </td> </tr> </table>	MATERIAL RELATIONS	RELATION	<p><i>Please, give the name of the Material Relation and which PE it completes.</i></p>	PHYSICAL QUANTITIES	<p><i>Please give the name of the physics quantities, parameters (constants, matrices) and variables that appear in the MR(s)</i></p>
	MATERIAL RELATIONS		RELATION	<p><i>Please, give the name of the Material Relation and which PE it completes.</i></p>		
		PHYSICAL QUANTITIES	<p><i>Please give the name of the physics quantities, parameters (constants, matrices) and variables that appear in the MR(s)</i></p>			
<p style="text-align: center;">SIMULATED INPUT</p> <p><i>Please document the simulated input and with which model it is calculated.</i></p> <p><i>This box documents the interoperability of the models in case of sequential or iterative model workflows. Simulated output of the one model is input for the next model. Thus what you enter here will also appear as processed output of the model that calculated this input.</i></p> <p><i>If you do simulations in isolation, then this box will remain empty.</i></p>						

MODEL 1, 2, ..., N (one for each model in the chain)	SOLVER AND TRANSLATION OF THE SPECIFICATIONS		
	NUMERICAL SOLVER	<p>Please give name and type of the solver.</p> <p><i>e.g. Monte Carlo, SPH, FE, iterative, multi-grid, adaptive,...</i></p>	
	SOFTWARE TOOL	<p>Please give the name of the code and if this is your own code, please specify if it can be shared with an eventual link to a website/publication.</p>	
	TIME STEP	<p>If applicable, please give the time step used in the solving operations.</p> <p>This is the numerical time step and this is not the same as the time lapse of the case to be simulated.</p>	
	COMPUTATIONAL REPRESENTATION	PHYSICS EQUATION	<p>Computational representation of the Physics Equation, Materials Relation and material.</p>
		MATERIAL RELATIONS	<p>There is no need to repeat User Case info. “Computational” means that this only needs to be filled in when your computational solver represents the material, properties, equation variables, in a specific way.</p>
		MATERIAL	
	COMPUTATIONAL BOUNDARY CONDITIONS	<p>Please note that these can be translations of the physical boundary conditions set in the User Case or they can be pure computational like e.g. a unit cell with mirror boundary conditions to simulate an infinite domain.</p>	
ADDITIONAL SOLVER PARAMETERS	<p>Please specify pure internal numerical solver details (if applicable), like specific tolerances, cut-off, convergence criteria.</p>		

MODEL 1, 2, ..., N (one for each model in the chain)	POST PROCESSING	
	THE PROCESSED OUTPUT	<p>The output obtained by the post processing (e.g. values for parameters, new MR and descriptor rules for data-based models).</p> <p>Specify the entity in the next model in the chain for which this output is calculated: electrons, atoms, beads (e.g. nanoparticles, grains), volume elements.</p> <p>In case of homogenisation, please specify the averaging volumes.</p>
	METHODOLOGIES	<p>Please describe the mathematics and/or physics used in this post-processing calculation (e.g. volume averaging, physical relations for thermodynamics quantities or optical quantities calculation)</p>
MARGIN OF ERROR	<p>Please specify the accuracy in percentages of the property calculated and explain the reasons to an industrial end-user.</p>	

Models based on **extraction/identification** of relations between descriptors using **data-mining** on simulated or experimental data.

They are **best-fitting, phenomenological models**. They are often called **surrogate models** in engineering.

These simplified relations when used in isolation **do not always need complicated numerical solvers** as they are able to find quick answers.

We will collectively call these relations **data-based models**. The database from which these relations are extracted should always be documented.

MODA
Application of a Data-based Model

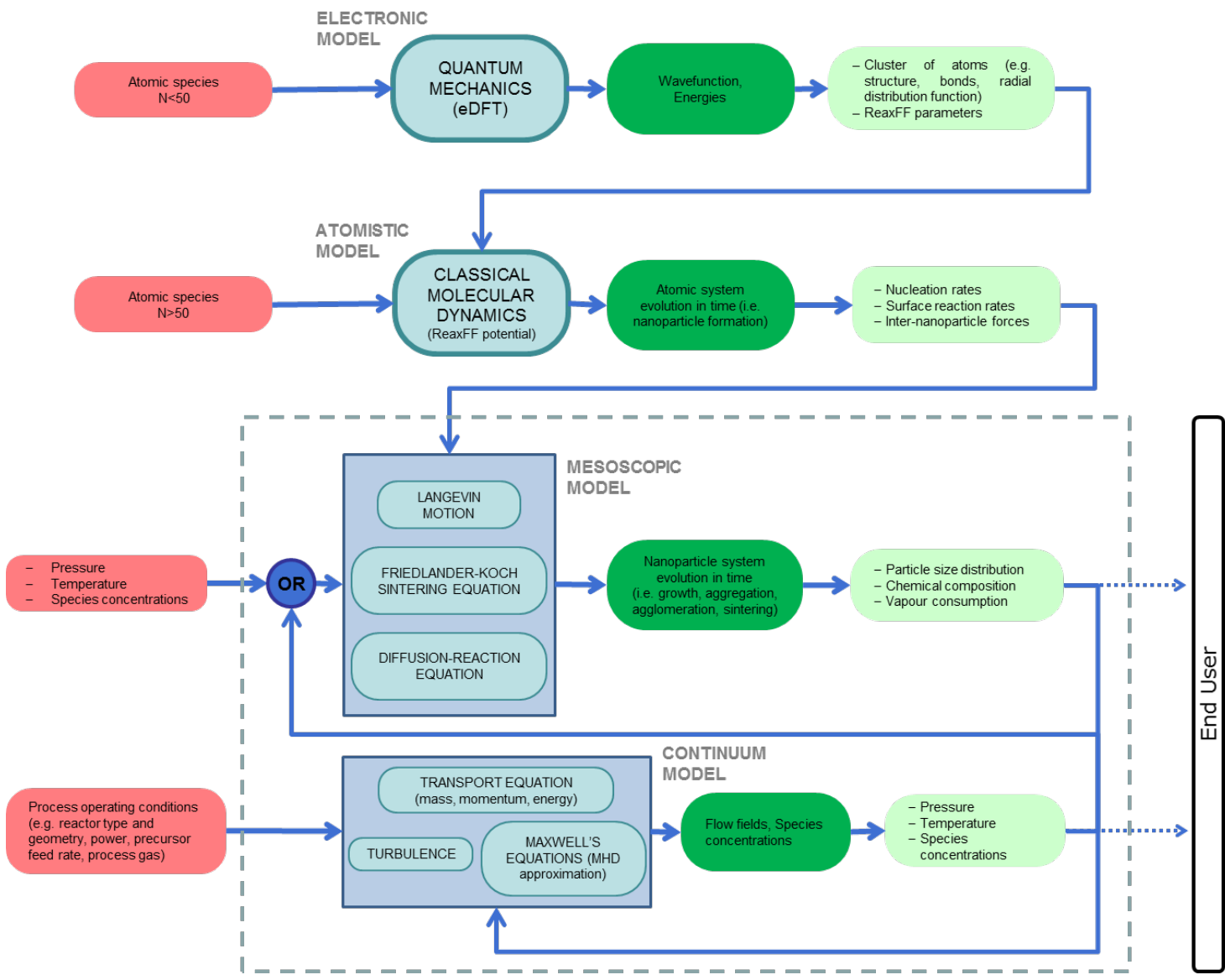
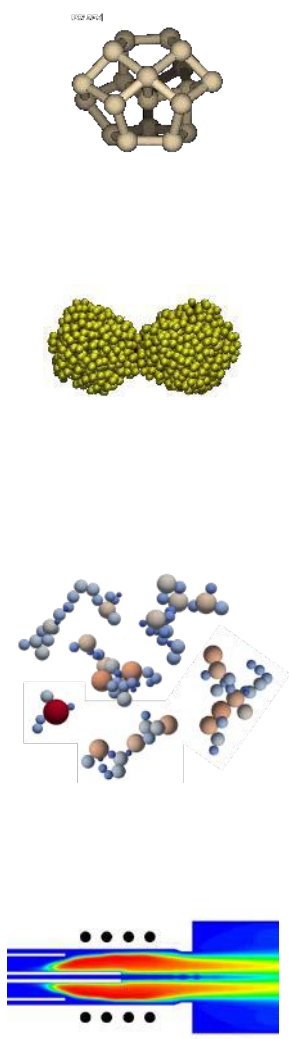
Please note that this MODA documents the use of a well-established data-based model (descriptor rule). It does not document the creation of such rules. Note that in simulation post-processing operations determining techniques can be used to find descriptor rules. These operations have to be documented in Chapter 4 of the physics-based MODA.

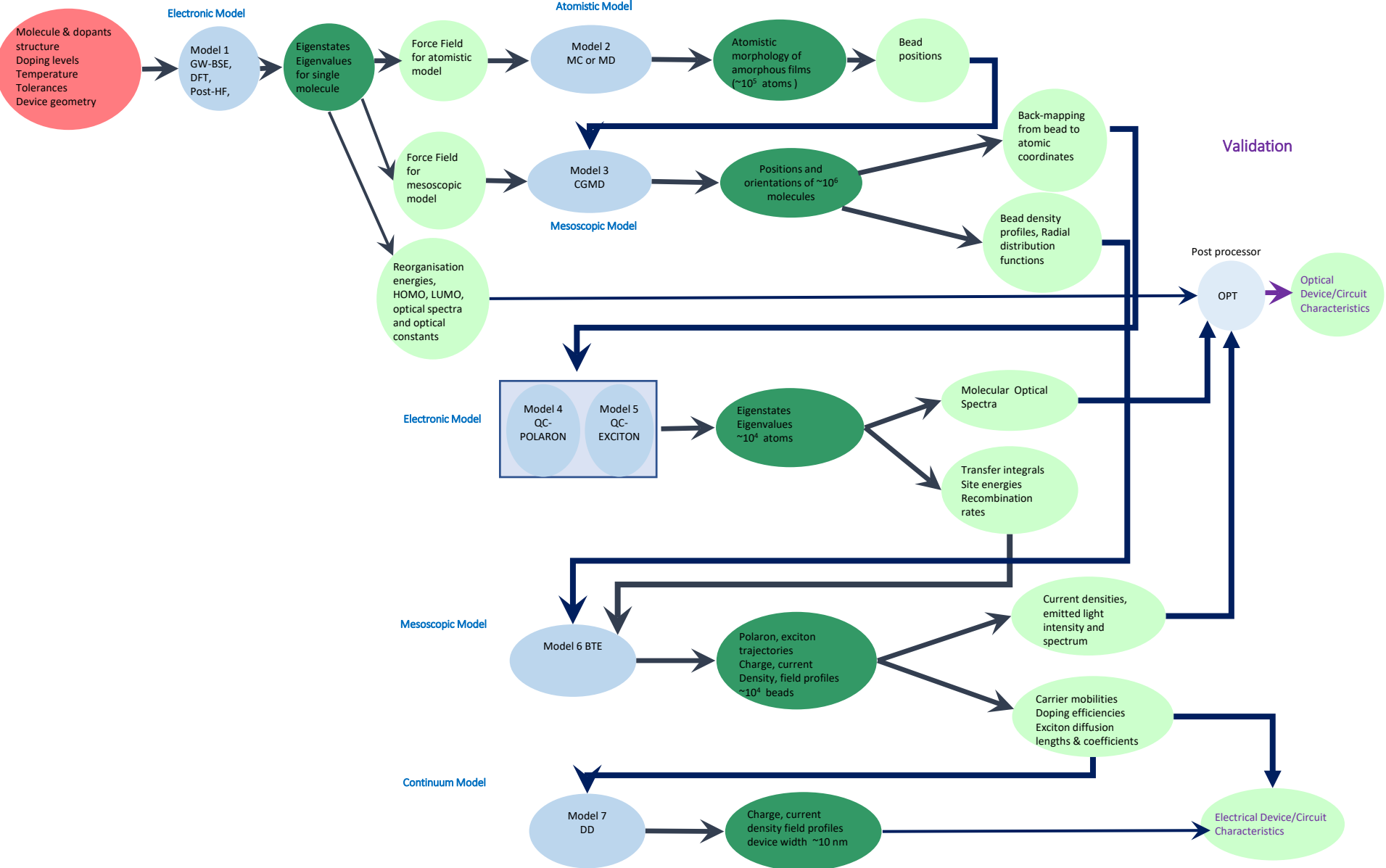
1 USER CASE:	
1.1	ASPECT OF THE USER CASE TO BE CALCULATED
1.2	MATERIAL
1.3	GEOMETRY
1.4	TIME LAWS (DURATION OF THE PROCESS TO BE DESCRIBED)
1.5	MANUFACTURING PROCESS OR SERVICE CONDITIONS
1.6	PUBLICATION OR THIS USE OF THE DATA-BASED MODEL

2 THE DATA-BASED MODEL	
2.0	<p>TOOL OR EQUATION TYPE AND NAME</p> <p>The equation could e.g. be for steady state creep in a material:</p> $\frac{\dot{\epsilon}}{\dot{\epsilon}_0} = \left(\frac{\sigma}{\sigma_0} \right)^n \exp\left(-\frac{Q}{RT}\right)$ <p>This equation would be used to measure or predict steady state creep rate $\dot{\epsilon}$ of a material at different temperatures T and subjected to steady uniaxial creep stress σ.</p> <ul style="list-style-type: none"> $\dot{\epsilon}$ = steady state creep strain rate = output quantity (dependent variable) $\dot{\epsilon}_0$ = reference strain rate. Fitted for a particular system. (parameter) σ_0 = reference stress. Fitted for a particular system. (parameter) n = power law exponent. Fitted for a particular system. (parameter) σ = applied stress (independent variable) Q = activation energy. Fitted for a particular system (parameter) R = universal gas constant T = Temperature (independent variable) <p>Tool could e.g. neural network?</p>
	<p>PHYSICS QUANTITIES IN THE DATA:</p>

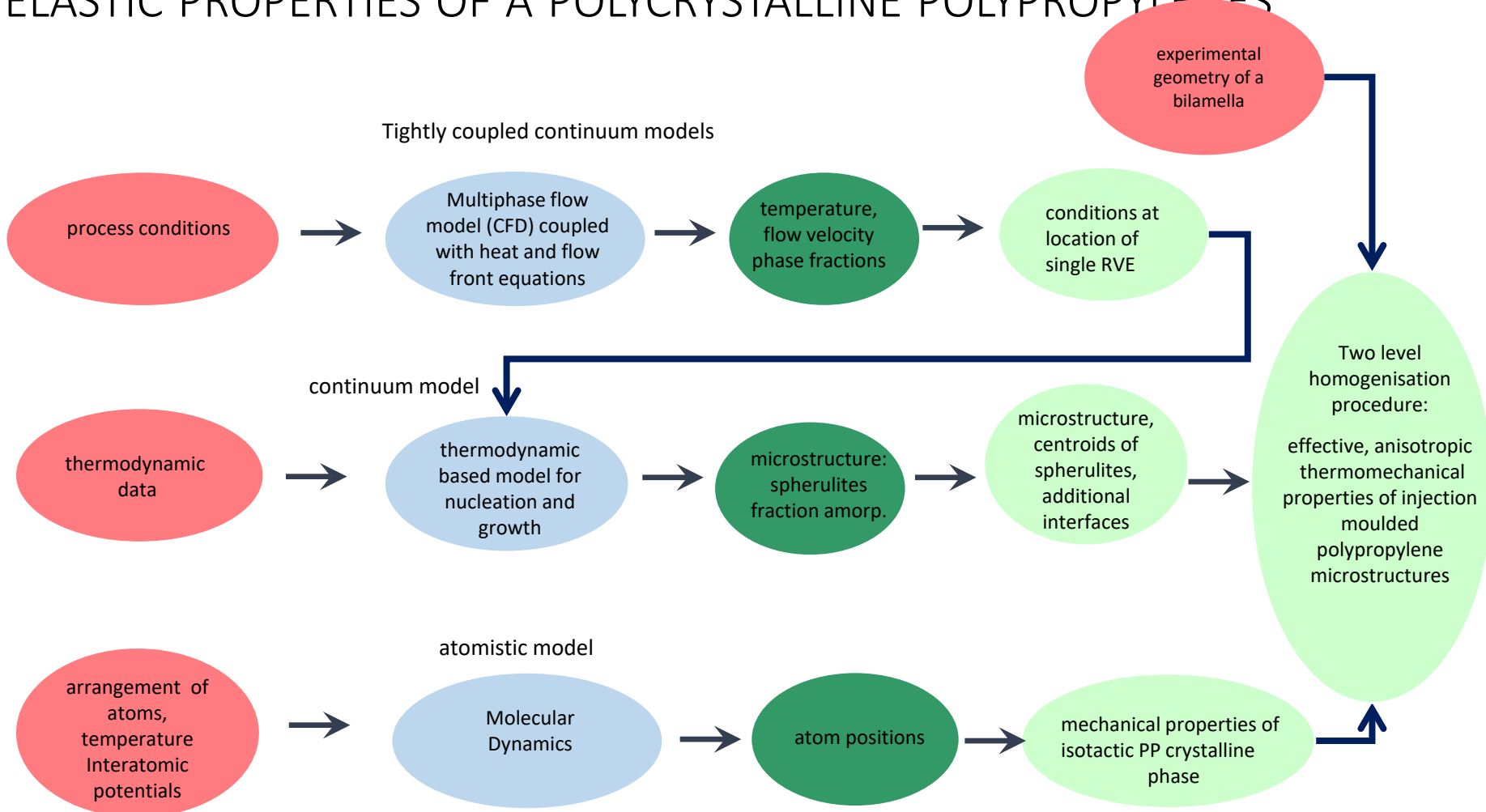
3 COMPUTATIONAL DETAIL OF DATA-BASE APPLICATION	
3.1	NUMERICAL OPERATIONS
3.2	SOFTWARE TOOL
3.3	MARGIN OF ERROR

USE CASE





ELASTIC PROPERTIES OF A POLYCRYSTALLINE POLYPROPYLENES



user case input

model

raw output

processed output

Functioning & stability-limiting mechanisms
organic phosphorescent OLEDs

Electronic model

Model 1
GW, BSE
~ 10² atoms

Relaxed geometries
Wave functions
Eigenenergies

Polarizable force fields

Excitation DOS's
Reorganization energies
Transfer Integrals

Model 2
MD
~ 10⁴ - 10⁵ atoms

Atomic positions

Amorphous morphology
Electrostatic & polarization contribution to site energies

Mesoscale model

Model 3
BTE
~ 10⁶ - 10⁷ sites

Time-dependent positions and distributions of quasiparticles

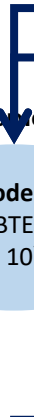
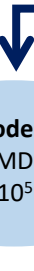
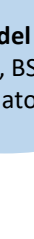
Charge mobilities
Exciton diffusion coefficients
Recombination & generation rates
Exciton decay rates
Charge-exciton & exciton-exciton quenching rates

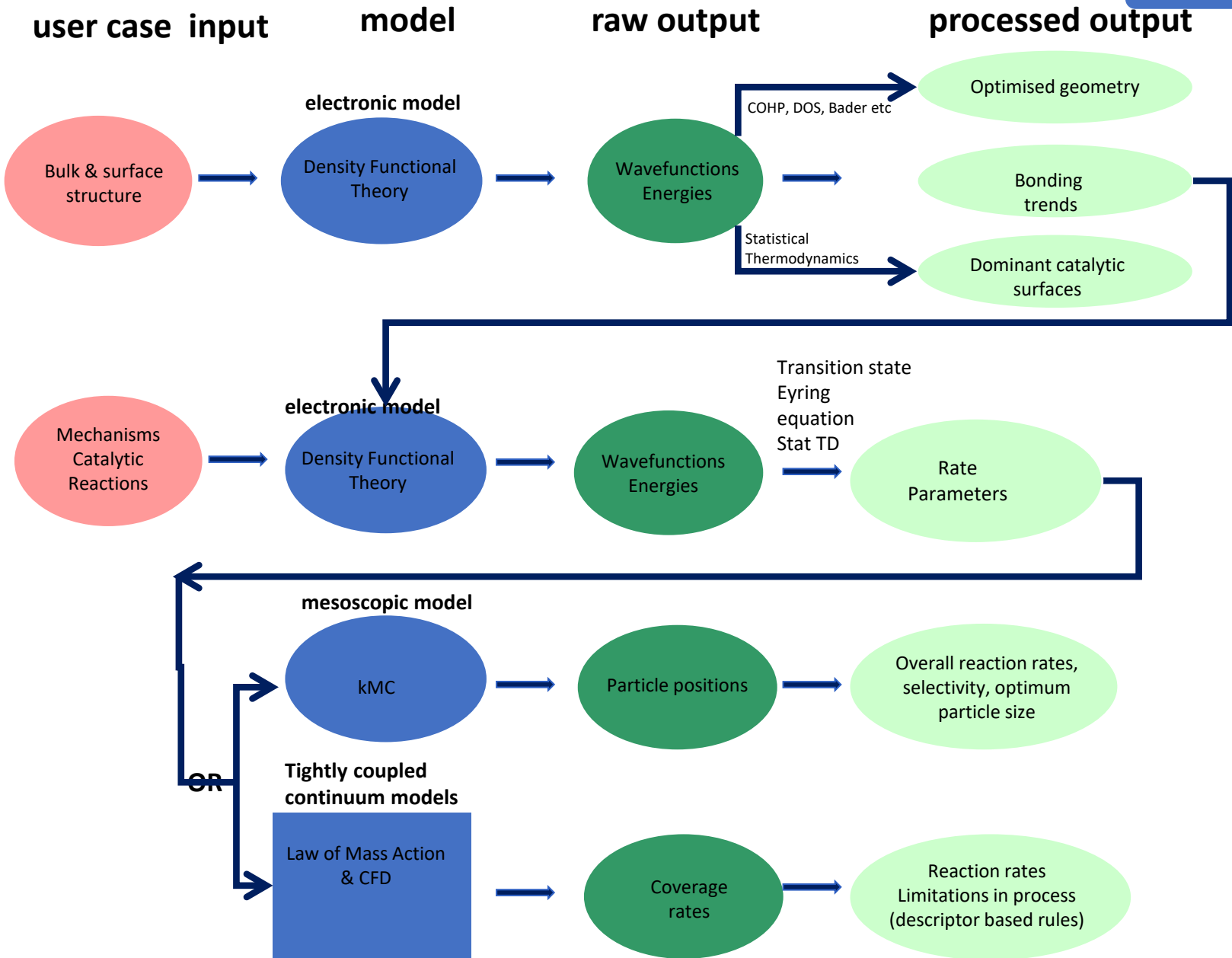
Continuum model

Model 4
DD

Time-dependent distributions of quasiparticles

Current- & luminescence-voltage characteristics
Luminescence efficiency & roll-off
Emission profile & colour balance
Degradation rate





RoMM taxonomy (vocabulary and classification) of material modelling
RoMM can be the basis for a top-level (upper) ontology (structure of knowledge)
MODA describes all aspects of a material simulation (workflow) with RoMM taxonomy

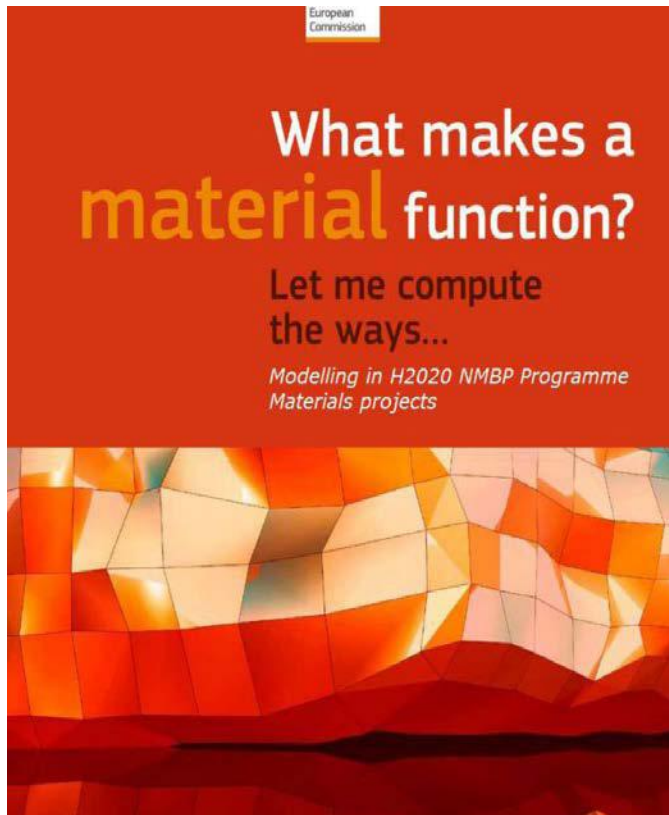
Metadata are defined as data and schema that describe and give information about a data describing a specific domain knowledge.

MODA as top-level METADATA SCHEMA

- **exchange of information** between materials modelling models (can also be in the same code)
- putting data in a form that allows modellers to **recognise** them along with their meaning.
- deal with the complexity of **sharing data between multiple tools** (in-house and commercial; proprietary and open)
- **code generation** (meta-programming of classes and structures)

- Develop MODA online form for easy compilation, catalogue and formatting.
 - Distinguish between free text field entries (e.g. description) and fixed options (e.g. model entities)
 - Provide standard PE for the 24 model types so that every applicant will not need to reinvent the wheel
 - Provide a first set of standard MR for the most common models
- Provide a navigable selected set of MODA examples (from RoMM VI) for different fields of applications to be used as reference point
- Develop formal taxonomy and ontology

YOU CAN FIND ALL THESE THINGS
EXTENSIVELY EXPLAINED
IN THE RoMM VI



**Modelling in
H2020 LEIT-NMBP Programme
Materials and Nanotechnology projects**

THANKS FOR YOUR ATTENTION

Review of Materials Modelling VI
RoMM

Edited by **Anne F de Baas**

Vocabulary, classification and metadata for materials modelling
(130 FP7 and H2020 projects)

<https://bookshop.europa.eu/en/what-makes-a-material-function--pbKI0616197/>

Short version of RoMM VI

<https://bookshop.europa.eu/en/what-makes-a-material-function--pbKI0417104/>